



## Moving Forward with SysML v2 October 19, 2022

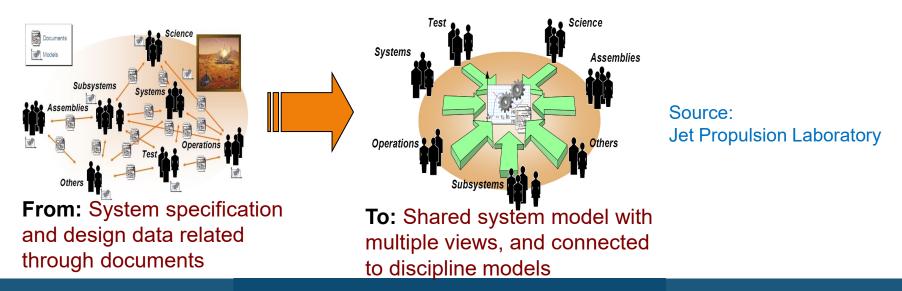
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## Model-Based Systems Engineering (MBSE)



- A systems engineering approach where information about the system is captured in a system model
  - The model is the source of the data and managed throughout the lifecycle
- Contrasts with a document-based approach where the information is captured in a variety of documents, informal diagrams, and spreadsheets
- Provides a more complete, consistent, and traceable system design





## SysML v2 Objectives

#### • Increase adoption and effectiveness of MBSE by enhancing...

- Precision and expressiveness of the language
- Consistency and integration among language concepts
- Interoperability with other engineering models and tools
- Usability by model developers and consumers
- Extensibility to support domain specific applications
- Migration path for SysML v1 users and implementors



## Key Elements of SysML v2



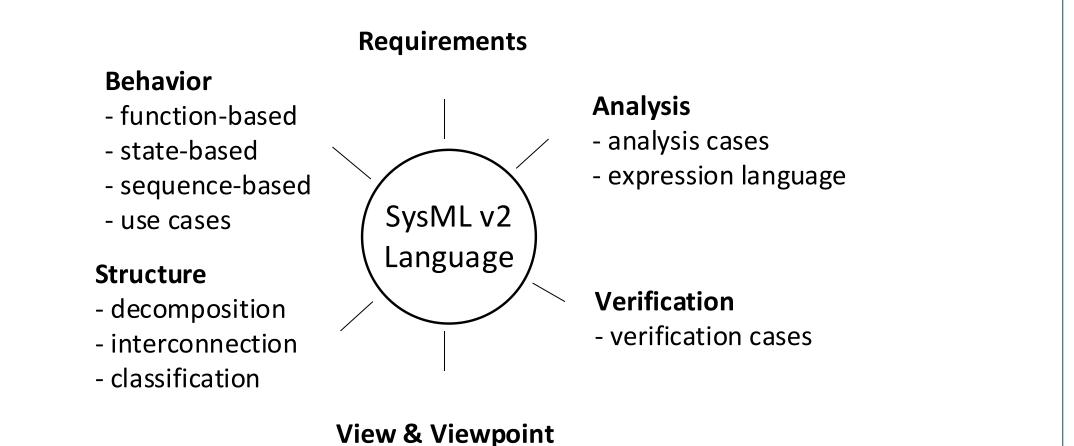
#### New Metamodel that is not constrained by UML

- Preserves most of UML modeling capabilities with a focus on systems modeling
- Grounded in formal semantics
- Robust visualizations based on flexible view & viewpoint specification and execution
   O Graphical, Tabular, Textual
- Standardized API to access the model



## SysML v2 Language Capabilities







## Vehicle Part Definition Replaces SysML v1 Block



- The vehicle part definition is characterized by different kinds of features including
  - Attributes
  - O Ports
  - Actions
  - O States

0 ...

«part def» Vehicle
attributes
mass :> ISQ::mass = dryMass + cargoMass + fuelMass dryMass :> ISQ::mass cargoMass :> ISQ::mass uelMass :> ISQ::mass position :> ISQ::length velocity :> ISQ::length velocity :> ISQ::speed acceleration :> ISQ::acceleration avgFuelEconomy :> distancePerVolume electricalPower :> ISQ::power
ports
uelCmdPort :FuelCmdPort gnitionCmdPort:IgnitionCmdPort /ehicleToRoadPort:VehicleToRoadPort
perform actions
providePower
exhibit states
vehicleStates



## Vehicle Part Definition Textual Syntax



• The textual syntax reflects the same model as the graphical syntax

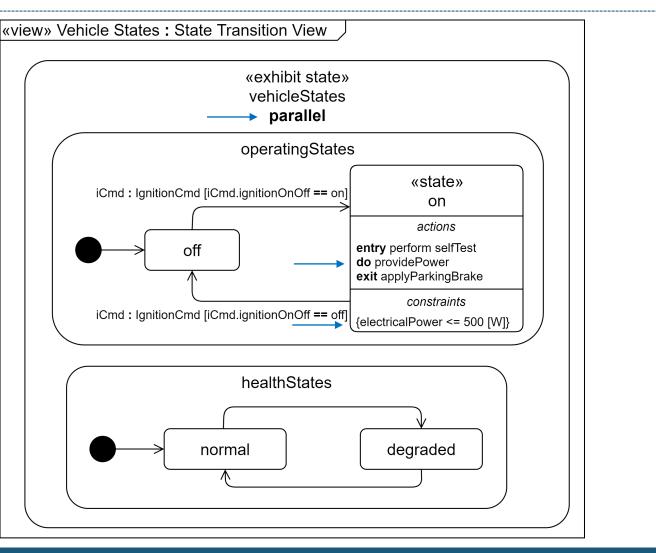
```
part def Vehicle{
    attribute mass :> ISQ::mass = dryMass + cargoMass + fuelMass;
    attribute dryMass:>ISQ::mass;
    attribute cargoMass:>ISQ::mass;
    attribute fuelMass:>ISQ::mass;
    attribute position:>ISQ::length;
    attribute velocity:>ISQ::speed;
    attribute acceleration:>ISQ::acceleration;
    attribute avgFuelEconomy:>distancePerVolume;
    attribute electricalPower:> ISQ::power;
    port fuelCmdPort:FuelCmdPort;
    port ignitionCmdPort:IgnitionCmdPort;
    port vehicleToRoadPort:VehicleToRoadPort;
    perform action providePower;
    exhibit state vehicleStates parallel {↔}
```



## **Vehicle States**



- States are hierarchical and can include:
  - parallel states (e.g., concurrent states) and mutually exclusive states
  - entry, exit, and do actions
  - o constraints





## **Vehicle States**

## **Textual Syntax**

```
exhibit state vehicleStates parallel {
    state operatingStates {
        entry action initial;
        state off;
        state on {
            entry action performSelfTest;
            do providePower;
            exit action applyParkingBrake;
            constraint {electricalPower<=500[W]}</pre>
        transition initial then off;
        transition off To on
            first off
            accept ignitionCmd:IgnitionCmd via ignitionCmdPort
                if ignitionCmd.ignitionOnOff==IgnitionOnOff::on
            then on;
        transition on To off
            first on
            accept ignitionCmd:IgnitionCmd via ignitionCmdPort
                if ignitionCmd.ignitionOnOff==IgnitionOnOff::off
            then off;
    state healthStates {
        entry action initial;
        state normal;
```

state degraded;

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## SysML v2 Reuse Patterns

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#### Definition and usage

- A definition element defines an element such as a part, action, or requirement
- A usage element is a usage of a definition element in a particular context
- Pattern is applied consistently throughout the language

#### • Variability

- Variation points represent elements that can vary
  - Variation applies to all definition and usage elements
- A variant represents a particular choice at a variation point
- A choice at one variation point can constrain choices at other variation points
- A system can be configured by making choices at each variation point consistent with the specified constraints



## Vehicle Part Defined by Vehicle Part Definition



• Parts are specializations of their definitions (defined by)

• Enables adaptation of each usage to its context by inheriting and redefining its features

«part» vehicle_1	<pre></pre>
attributes	attributes
<pre>^mass dryMass :&gt;&gt; dryMass = sum (partMasses); partMasses=(engine.mass,transmission.mass); ^cargoMass ^fuelMass ^position ^velocity ^acceleration ^avgFuelEconomy ^electricalPower</pre>	mass :> ISQ::mass = dryMass + cargoMass + fuelMass dryMass :> ISQ::mass cargoMass :> ISQ::mass fuelMass :> ISQ::mass position :> ISQ::length velocity :> ISQ::speed acceleration :> ISQ::acceleration avgFuelEconomy :> distancePerVolume
ports	electricalPower :> ISQ::power
<ul> <li>fuelCmdPort : FuelCmdPort</li> <li>ignitionCmdPort : IgnitionCmdPort</li> <li>vehicleToRoadPort : VehicleToRoadPort</li> </ul>	<i>ports</i> fuelCmdPort : FuelCmdPort
<pre>perform actions providePower :&gt; ActionTree :: providePower :&gt;&gt; Vehicle::providePower</pre>	ignitionCmdPort : IgnitionCmdPort vehicleToRoadPort : VehicleToRoadPort
exhibit states	perform actions providePower
parts	exhibit states
engine : Engine transmission : Transmission	vehicleStates



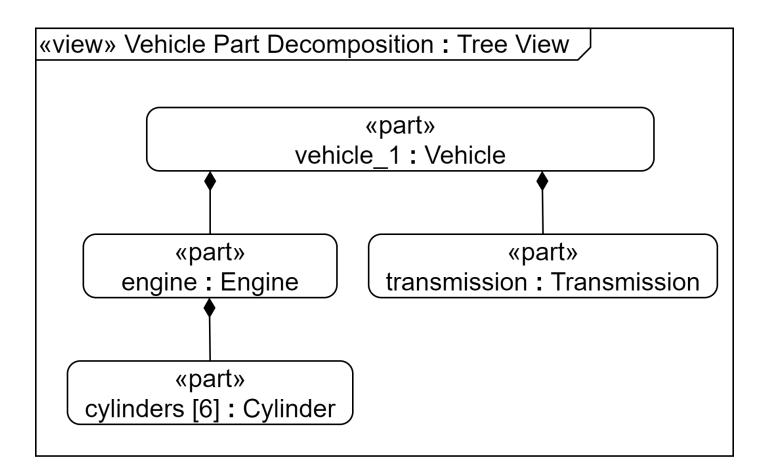
## Vehicle Part Textual Syntax



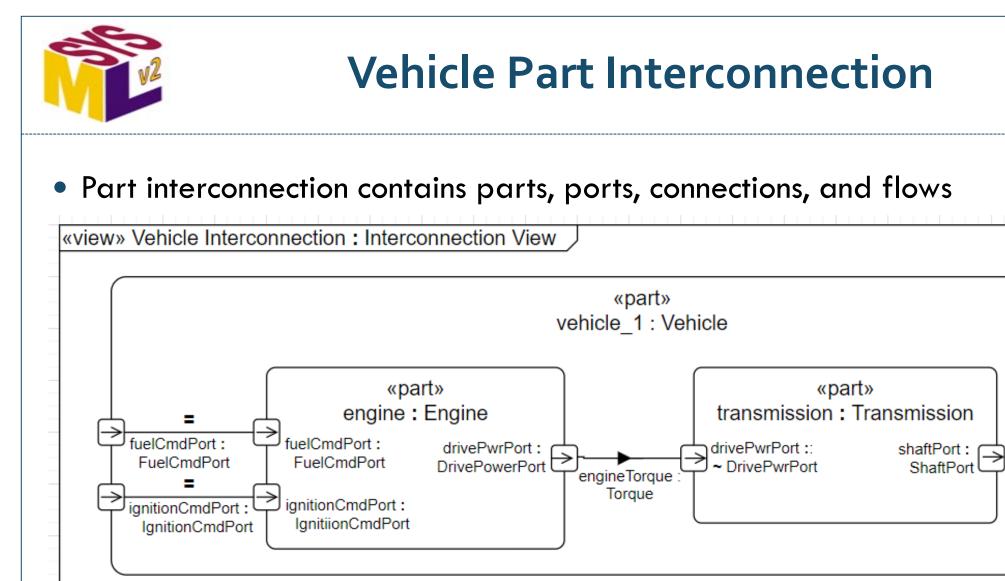
```
part vehicle 1:Vehicle{
                  attribute mass redefines mass;
                  attribute dryMass redefines dryMass = sum (partMasses);
                  attribute partMasses=(engine.mass,transmission.mass);
                  perform ActionTree::providePower redefines providePower;
nested part
                  part engine:Engine{
                      attribute mass redefines mass default 200 [kg];
                      port fuelCmdPort:>>fuelCmdPort=vehicle 1.fuelCmdPort;
                      port ignitionCmdPort:>>ignitionCmdPort=vehicle 1.ignitionCmdPort;
                      perform ActionTree::providePower.generateTorque;
                      part cylinders[6]:Cylinder;
                  part transmission:Transmission{
                      attribute mass redefines mass default 60 [kg];
                      perform action amplifyTorque:>> amplifyTorque = ActionTree::providePower.amplifyTorque;
connection
                  connect engine.drivePwrPort to transmission.drivePwrPort;
```



## **Vehicle Part Decomposition**



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vehicleToRoadPort

VehicleToRoadPort

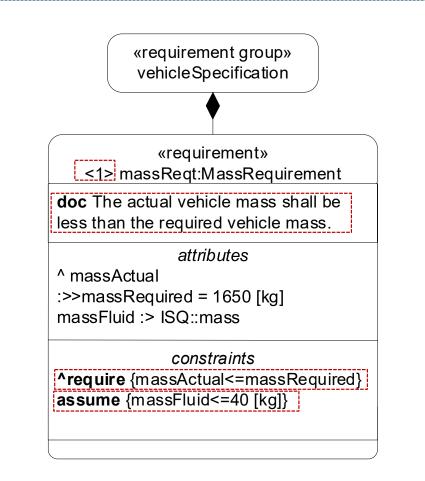
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## Requirements



- A constraint definition that a valid design solution must satisfy that can include:
  - Identifier
  - Shall statement
  - Constraint expression that can be evaluated to true or false
    - can apply to performance, functional, interface and other kinds of requirements if desired
  - Assumed constraint expression that is asserted to be true for the requirement to be valid







#### • Each entity has a lifetime

- Reference clock
- $\odot$  Can specify timeslices and snapshots
- Spatial entities have spatial extent over different parts of their lifetime
  - $\odot$  Specified by shapes with position and orientation within coordinate frames
- Individuals
  - $\ensuremath{\circ}$  Unique identify with a lifetime



## SysML v2 to v1 Terminology Mapping (partial)

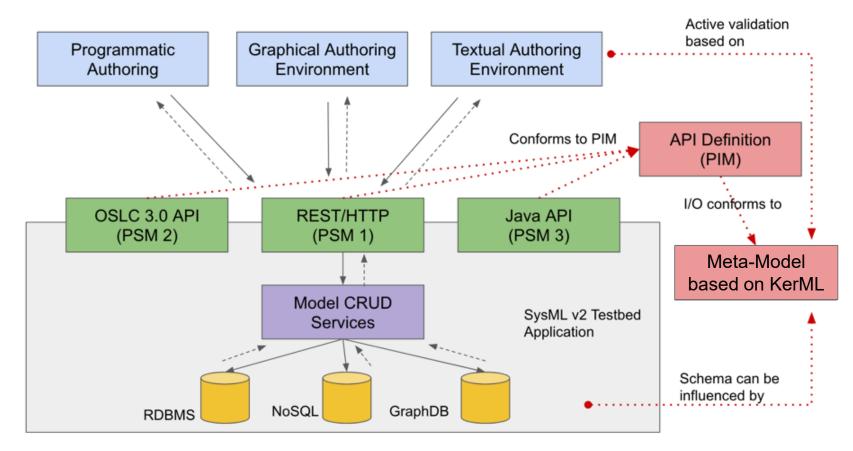


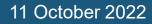
SysML v2	SysML v1
part / part def	part property / block
attribute / attribute def	value property / value type
port / port def	proxy port / interface block
action / action def	action / activity
state / state def	state / state machine
constraint / constraint def	constraint property / constraint block
requirement / requirement def	requirement
connection / connection def	connector / association block
view / view def	view



## SysML v2 Pilot Implementation Using Standard API

### High-Level Architecture of SysML v2 Testbed

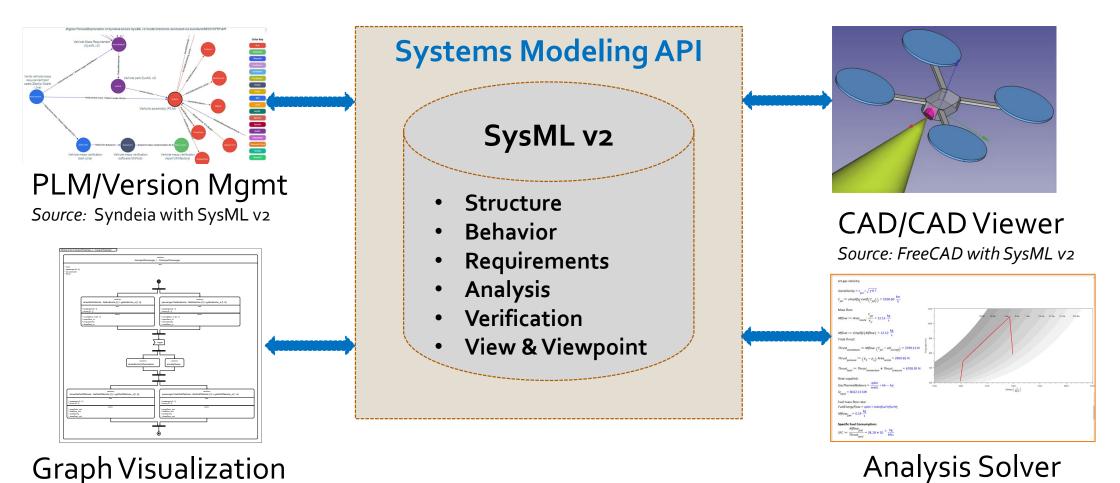




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## Connecting SysML v2 through the API SS7



Source: Tom Sawyer with SysML v2

11 October 2022

Source: Maple with SysML v2



## Contrasting SysML v2 with SysML v1

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- Simpler to learn and use
  - Systems engineering concepts designed into metamodel versus added-on
  - Consistent application of definition and usage pattern
  - More consistent terminology
  - Ability to decompose parts, actions,
  - More flexible model organization (unowned members, package filters)...
- More precise
  - Textual syntax and expression language
  - Formal semantic grounding
  - Requirements as constraints

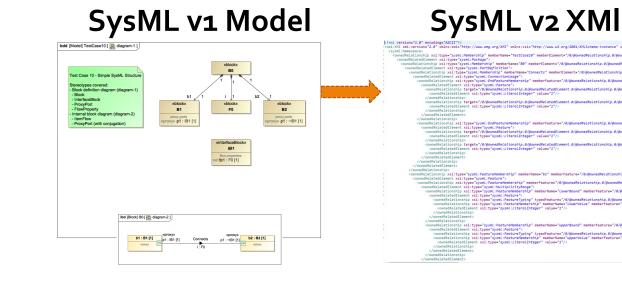
#### • More expressive

- Variant modeling
- O Analysis case
- Trade-off analysis
- Individuals, snapshots, time slices
- O More robust quantitative properties (e.g., vectors, ..)
- $\odot$  Simple geometry
- $\circ$  Query/filter expressions
- 0 Metadata
- More extensible
  - Simpler language extension capability
    - Based on model libraries
- More interoperable
  - O Standardized API

# V2

## SysML v1 to SysML v2 Transformation

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Source: SST Track 3 Presentation Yves Bernard, Tim Weilkiens o8 February 2022

#### SysML v2 Textual Notation

#### package eVehicleLibrary

attribute def ElectricEnergy; attribute def BatteryCapacity :> ScalarValues::Integer; attribute def Speed :> ScalarValues::Integer; port def PowerOutPort { out energy : ElectricEnergy;

interface def PowerInterface {
 end supplierPort : PowerOutPort;
 end consumerPort : ~PowerOutPort;

```
package eVehicleDefinitions {
    import eVehicleLibrary::*;
part def Wheel {
    value size : ScalarValues::Integer;
}
part def Battery {
```

value capacity : BatteryCapacity;

```
. . . . .
```

part def Engine;



## SysML v2 Milestones

December, 2017	SysML v2 RFP issued
June, 2018	SysML v2 API & Services RFP issued
August, 2020	Initial Submission
February, 2021	Stakeholder Review
August, 2021	Revised Submission
November, 2021	2nd Revised Submission (OMG evaluation initiated)
November, 2022	3 <sup>rd</sup> Revised Submission
1st Qtr 2023	Final Submission (beta specification)
2024	Adopted Specification (pending OMG approvals)

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## Summary





## Summary



- SysML v2 is addressing SysML v1 limitations to improve MBSE adoption and effectiveness
  - Precision, expressiveness
  - Regularity, usability
  - Interoperability with other engineering models and tools
- Approach
  - SysML v2 metamodel with formal semantics architected to overcome fundamental UML limitations
  - $\,\circ\,$  Flexible graphical notations and textual notation
  - Standardized API for interoperability
  - $\odot\,$  Transformation specification from SysML v1 to SysML v2
- Plan
  - Final submission (beta specification) Q1 2023
  - Final adopted specification 2024



## SST Public Repositories Current Release: 2022-08

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- Monthly release repository
  - o https://github.com/Systems-Modeling/SysML-v2-Release
- Release content
  - Specification documents (for KerML, SysML and API)
  - Training material for SysML textual notation
  - Training material for SysML graphical notation
  - Example models (in textual notation)
  - Pilot implementation
    - Installer for Jupyter tooling
    - Installation site for Eclipse plug-in
  - Web access to prototype repository via SysML v2 API
  - Web access to Tom Sawyer visualization tooling
- Open-source repositories
  - o <u>https://github.com/Systems-Modeling</u>
- Google group for comments and questions
  - <u>https://groups.google.com/g/SysML-v2-Release</u> (to request membership, provide name, affiliation and interest)





## Questions

